

# High voltage gain DC-DC resonant converter

M. A. Shamsinejad, R. Zare, M. Ramazani

**Abstract --In this paper, a DC-DC resonant converter with high voltage gain and small size is studied. To reduce the size and weight of this converter, the operating frequency should be as high as possible. In this research, the frequency changes from 120 to 200 kHz. Due to the high operating frequency, it is necessary to reduce the switching losses using soft switching methods. Resonant converters are suitable choice for this purpose. Since the output voltage is high, the series structure can be a good choice.**

**Index Terms - DC-DC Resonant converter, High voltage, Soft switching, Series-Parallel.**

## I. INTRODUCTION

**P**ERFORMANCE of DC-DC resonant converter with high output voltage is significantly affected by the non-ideal transformer with high conversion rate. The secondary windings is one of the resonant elements. Both leakage inductance and parasitic capacitance of windings can have a significant effect on the behavior of converters. Thus a good topology with high voltage gain is one that has possibility of removing these noises. The DC-DC resonant converter is a suitable choice for high voltage gain. Because they can use leakage inductance and capacitance of transformer windings as part of resonance circuit. Soft switching techniques can also be used to eliminate or reduce the switching losses. Moreover in this research, the series-parallel resonant converter is selected because it has advantages of both series and parallel converters and moreover it hasn't disadvantages of them.

The design and control of resonant converters are complicate. In this paper we present a simple method to design a high voltage gain DC-DC resonant converter. This method is based on the analysis of the first harmonic. The output power can be controlled by changing the duty cycle. The frequency is automatically adjusted to ensure optimal commutation. This method is named "variable frequency phase shift control" [1- 4].

In the following, the power circuit of resonant converter determined and analyze of its behavior and the stress on the elements are calculated. The simulation results for a 5kW/15kV resonant converter with operating frequency of 120 kHz at low load and 200 kHz at full load are presented. Finally the simulation results are validated by experimental tests.

## II. SERIES-PARALLEL RESONANT CONVERTER

There are different topologies for resonant converter. In this research, a resonant converter with 1 inductor and 2 capacitors (LCC) is studied [5, 9]. At frequencies higher than the resonant frequency, the parallel capacitor  $C_p$  helps to increase the voltage. Equation (1) indicates the voltage gain of the converter with the approximation proposed in [10].

$$\frac{V_o}{nV_{in}} = \frac{4 k_{21}}{\pi k_v} \tag{1}$$

$$k_{21} = \frac{V_{Cp(1)}}{V_{AB(1)}} = \frac{1}{\sqrt{[1-\alpha(f_{sn}^2-1)]\left(1+\frac{\tan(\beta)}{\omega C_p R_e}\right)^2 + [\alpha(f_{sn}^2-1)\frac{1}{\omega C_p R_e}]^2}} \tag{2}$$

$$k_v = 1 + 0.27 \sin \frac{\theta}{2} \tag{3}$$

$$\alpha = \frac{C_p}{C_s} \tag{4}$$

$$f_{sn} = f_s / f_o \tag{5}$$

$$f_o = 1 / (2\pi \sqrt{L_s C_s}) \tag{6}$$

In these equations:

- $n$  Conversion rate of transformer
- $k_v$  Coefficient between the output voltage referred to the primary side and the amplitude of first harmonic of  $V_{Cp}$
- $\beta$  Phase angle between first harmonic of transformers current and voltage
- $R_e$  Equivalent resistance of converter RC model
- $f_{sn}$  Normalized switching frequency
- $f_s$  Switching frequency
- $f_o$  Series resonant frequency

Fig.1. presents a full bridge, series-parallel DC-DC resonant converter, with high voltage gain which operates at frequency over than resonant frequency.

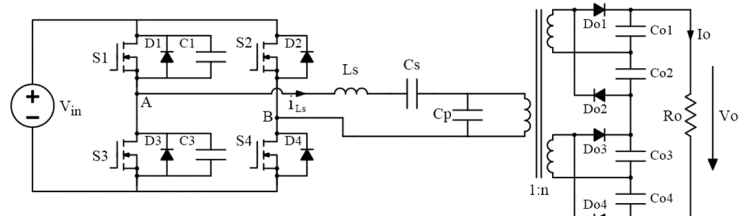


Fig.1. Series-Parallel resonant converter

In this converter, the operating frequency depends on the load variations. Because, the load determines the effect of capacitor  $C_p$ . In full load, only a small part of resonance current pass from parallel resonant capacitor  $C_p$ . So it acts as a series resonant converter and resonant

Mohammad Ali Shamsinejad ([m\\_sh\\_80@yahoo.com](mailto:m_sh_80@yahoo.com)), Reza Zare and Mohsen Ramazani are with Faculty of Electrical and Computer Engineering, The University of Birjand, Birjand, Iran

frequency is approximately equal to the resonant frequency of the series converter. Similarly, in small load, a small part of resonance current pass from series resonant capacitor  $C_s$ . So it acts as a parallel resonant converter.

### III. CIRCUIT ANALYSIS

Capacitors  $C_1$  and  $C_3$  help to zero voltage switching of power MOSFETs  $S_1$  and  $S_3$  in turn off mode. Resonant inductor  $L_s$  is the sum of transformer leakage inductance with a series external inductance. Parallel resonant capacitor  $C_p$  is also the sum of parasitic capacitor of the secondary coils of the transformer and an auxiliary capacitor. Equivalent circuit of series-parallel resonant converter is shown in Fig.2. In this figure, the output quantities of transformers delivered to its primary. Diodes  $D_1, D_2, D_3$  and  $D_4$ , are the internal diode of power MOSFETs. Fig.3. indicates  $V_{AB}$  and resonance current of converter in optimal mode. Switches  $S_1$  and  $S_3$  become turn on in ZVS<sup>1</sup> mode (at  $t_2$  and  $t_4$ ). In the other leg of inverter, switches  $S_2$  and  $S_4$  become turn on in ZVS mode and turn off in ZCS<sup>2</sup> mode (at  $t_1$  and  $t_3$ ).

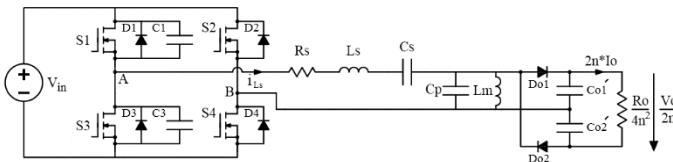


Fig.2. Equivalent circuit of series-parallel resonant converter

So there are no switching losses. The inverse diodes  $D_2$  and  $D_4$  don't conduct and in theory they are not necessary. But in experimental set, the commutation cannot be occurring in zero current and need to a dead time between 2 switch of each leg. Thus we cannot eliminate these diodes. Parasitic Capacitor of MOSFETs can be used as loss less snubber. Diodes  $D_1$  and  $D_3$  can be slower because there are not any direct current from freewheeling diodes to power switches. Thus the internal diode of MOSFET can be used as a freewheeling diode.

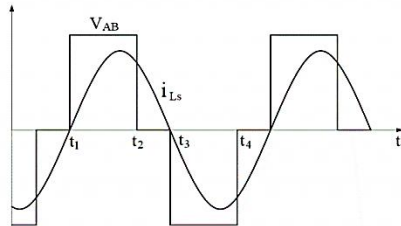


Fig.3. Optimum commutation mode

### IV. DESIGN OF SERIES-PARALLEL RESONANT CONVERTER

In this section, design of series-parallel resonant converter based on study of the first order harmonic is done. It can be finding from Fig.3. and Fig.4. that the resonance current  $i_{L_s}$  is almost sinusoidal. But the waveforms  $V_{AB}$ ,  $i_T$  and  $V_{C_p}$  haven't sinusoidal form. Since the power delivered to the load depends on the input voltage and resonance current  $i_{L_s}$  and due to the sinusoidal form of current  $i_{L_s}$ , only the first harmonic of voltage is important in power transmission. Thus the design

process based on the first harmonic of voltage correctly predicts the output power and the stress on the circuit elements. A simple and effective method presented by Ivenskyin [10]. He modeled the rectifier and capacitor filter with an RC circuit. The resonance current supposed sinusoidal (see Fig.3.). According to Fig.4.,  $V_{C_p}$  and input current of rectifier are not in phase.

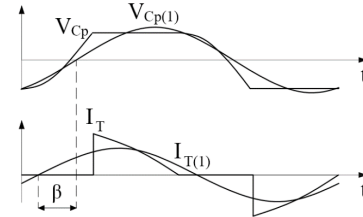


Fig.4. Voltage signal of  $C_p$  and input current of rectifier

The first harmonic of rectifier current is lead compare to parallel capacitor voltage.

Thus output load can be approximated by an RC load. Fig.5. illustrates this model.  $k_v$  is a coefficient between the output voltage of transformer referred to the primary side and the first harmonic of parallel capacitor voltage, which will be explain in the following.

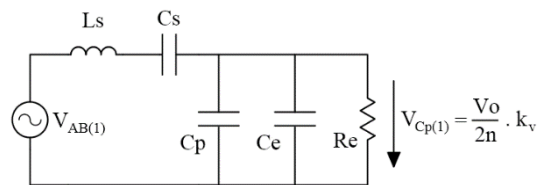


Fig.5. RC model of series-parallel resonant converter

$R_e$  and  $C_e$  (equivalent output resistance and capacitance of RC model) calculate by the following equations:

$$R_e = \frac{R_o k_v^2}{2n^2} \tag{7}$$

$$C_e = \frac{2n^2}{\omega R_o k_v^2} \tan(\beta) \tag{8}$$

Here after the equations of series-parallel resonant converter is going to calculate the stresses on the converter elements [11]. The main characteristic of the transducer is determined. We are going to design a converter with the following specification:

Input voltage 300 V, Output voltage 15 kV, Output current 0-300 mA, Output power 0 – 5 kW

According to the process described in [10] and with respect to the  $C_p$ ,  $n$  and output values, the output rectifier conduction angle obtain from the following equation.

$$\theta = 2 \tan^{-1} \left( \sqrt{\frac{4n^2}{f_s C_p R_o}} \right) = 2 \tan^{-1} \left( \sqrt{\frac{4n^2 I_o}{f_s C_p V_o}} \right) \tag{9}$$

$$\beta = -0.4363 \sin(\theta) \tag{10}$$

$$\omega C_p R_e = \frac{k_v^2 \cdot \pi}{4 \tan(\frac{\theta}{2})^2} \tag{11}$$

Inverter output voltage and Resonance current waveforms are shown in Fig.6. The first harmonic of inverter output voltage is:

$$V_{AB(1)} = \frac{4}{\pi} \cdot V_{in} \cdot \cos(\phi) \tag{12}$$

Where according to Fig.6,  $\phi$  is the phase between  $V_{AB(1)}$  and the resonance current calculate as follows:

<sup>1</sup>Zero Voltage Switching  
<sup>2</sup>Zero Current Switching

$$\phi = \tan^{-1} \left( \frac{\alpha}{\omega C_p R_e} \left[ f_{sn}^2 \left( 1 + [\omega C_p R_e + \tan |\beta|]^2 \right) - 1 \right] \right) \quad (13)$$

$$D = \gamma / \pi \quad (14)$$

$$\phi = \frac{\pi}{2} - \frac{D\pi}{2} \quad (15)$$

Where  $D$  represents the duty cycle of the converter, and  $\phi$  is the angle of the duty cycle.

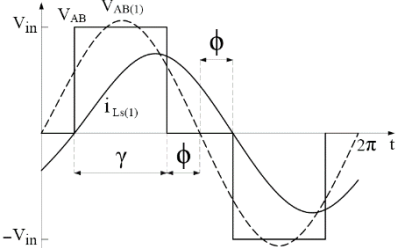


Fig.6. Phase angle between the first harmonic of output inverter voltage and resonance current

By mixing equations (13) and (15), the duty cycle calculates:

$$D = 1 - \frac{2}{\pi} \tan^{-1} \left( \frac{\alpha}{\omega C_p R_e} \left[ f_{sn}^2 \left( 1 + [\omega C_p R_e + \tan |\beta|]^2 \right) - 1 \right] \right) \quad (16)$$

Duty cycle described as a function of the normalized switching frequency  $f_{sn}$  and conduction angle  $\theta$ . By replacing equation (15) in (12), the inverter output voltage is:

$$V_{AB(1)} = \frac{4}{\pi} \cdot V_{in} \cdot \sin\left(\frac{D\pi}{2}\right) \quad (17)$$

Finally, the output voltage of resonant converter calculates by the following equation:

$$V_o = \frac{16}{\pi} \cdot \frac{k_{21}}{k_v} \cdot n \cdot V_{in} \cdot \sin\left(\frac{D\pi}{2}\right) \quad (18)$$

By the definite values of  $\alpha$ ,  $n$ ,  $V_{in}$ ,  $I_o$ ,  $V_o$  and resonant elements, the operating frequency calculate. So the parameters are calculable. For example, using the following equation, peak resonance current of inductor is:

$$I_{PLS} = \frac{f_{sn} \cdot \alpha}{2n(1 + \cos(\theta))} \cdot \frac{V_o}{Z_s} \quad (19)$$

$$Z_s = \sqrt{L_s / C_s} \quad (20)$$

Turn off current of  $S_1$  and  $S_3$  are:

$$I_{Soff} = I_{PLS} \cdot \sin(D\pi) \quad (21)$$

The RMS current of  $S_1$  and  $S_3$  switches are:

$$I_{Srms} = \frac{I_{PLS}}{2} \cdot \sqrt{D - \frac{\sin(2D\pi)}{2\pi}} \quad (22)$$

The series capacitor voltage is:

$$V_{PCs} = \frac{I_{PLS}}{2\pi \cdot f_s \cdot C_s} \quad (23)$$

The first step is designing the resonance circuit elements under constraints such as maximum stress on the elements or values of parasitic elements. The maximum duty cycle occur when the output current and power is maximum (330mA 5kW). It will be shown in the simulation results. Ideally, the maximum duty cycle is one ( $D=1$ ). But in order to imposed dead time between the switching, duty cycle is usually below 0.9. The designing process is an iterative method. The output voltage, input voltage, frequency and load resistance ( $R_{o, min}$ ,  $R_{o, max}$ ) is given. We have to do the following steps [12]. Designing process start from determination of  $V_{in}$  and  $R_{o, min}$  values.

1. Determine the value of  $\theta$ ,  $D$  and  $\alpha$ .

2. Calculation of Parameters  $k_v$ ,  $\beta$ ,  $\omega C_p R_o / n^2$ ,  $\omega C_p R_e$ ,  $f_{sn}$ ,  $k_{21}$  and  $n$ .
3. Calculation of  $C_p$  from equation  $\omega C_p R_o / n^2$  and  $C_s$  from  $\alpha = C_p / C_s$ , and  $L_s$  from equations (5) and (6).
4. Calculation of stress on the circuit elements.
5. Repeating the above steps for different values of  $\theta$ ,  $D$  and  $\alpha$ .
6. Repeating the steps 1 through 4 for  $V_{in}$ ,  $R_{o, max}$ .
7. The optimal values for  $\theta$ ,  $D$  and  $\alpha$  based on high efficiency, lower costs, lower weight and volume, smaller frequency range and appropriate stress.

## V. SIMULATION RESULTS

According to the Designing steps in the previous section, the simulation for the desired output voltage under low load and full load is done. Parameters used in the simulation are:  $P_o = 50$  kW,  $V_{in} = 300$  V,  $n = 12$  turn,  $C_1 = C_3 = 200$  pF,  $C_s = 39$  nF,  $C_p = 19$  nF,  $L_s = 60$  mH,  $C_{h1} = C_{h2} = C_{h3} = C_{h4} = 120$  nF. Simulation output voltage and current of series-parallel resonant converter is shown in Fig.7.

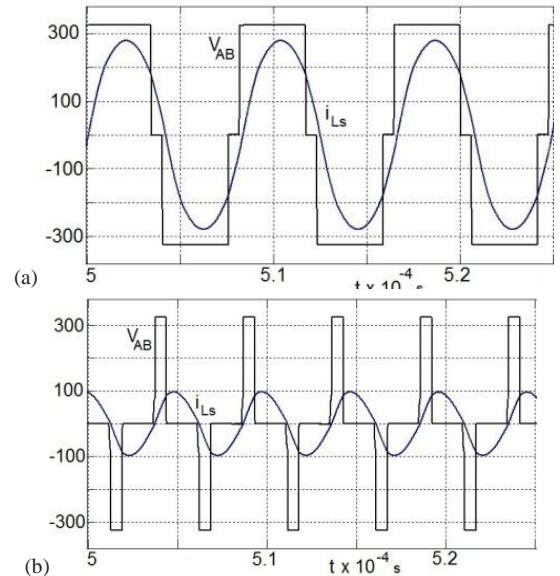


Fig.7. Output voltage and current of series-parallel resonant converter in (a) High load (The current multiplied by 10) (b) Low load (The current multiplied by 10)

Fig.8. shows the output voltage of converter.

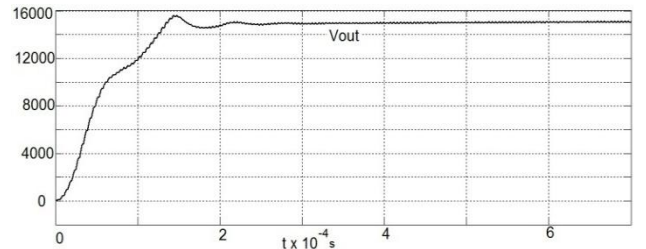


Fig.8. Output voltage of series-parallel resonant converter

## VI. EXPERIMENTAL SET

The elements values are the same as designed and used in simulation (section 5). Operating frequency is 120 – 200 kHz.

A Sawtooth generation

Due to the optimal commutation mode, switching frequency for the various set points should be strictly regulated. A sawtooth waveform with fix amplitude and variable frequency is necessary. To generating this signal, the idea of a closed loop can be used [13]. In this idea, a sawtooth produced by  $RP^1$  pulse which is coincident with the zero crossing of the current. Fig. 9. shows block diagram of this method, where the converter output voltage ( $V_c$ ) is the input of control circuit.

In order to design  $K_{p1}$  and  $K_{p2}$  coefficients in this figure, the equations that describe the behavior of the system should be solved. These coefficients should be determined so that the system response is quick and distortion level of sawtooth waveform is in an acceptable domain.

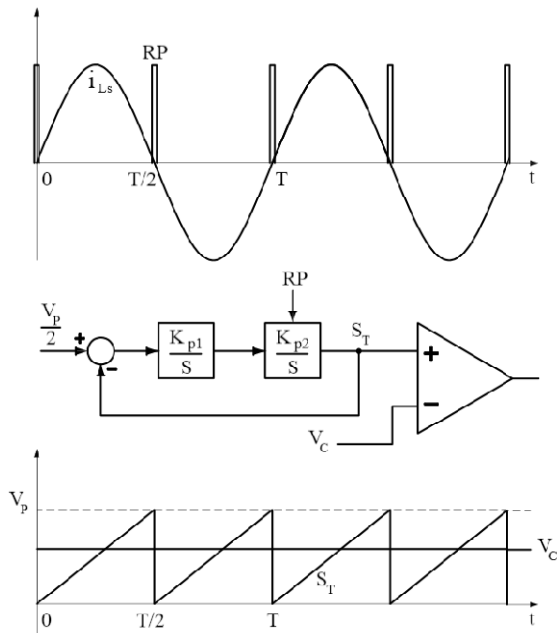


Fig.9.Sawtooth waveform with constant amplitude

Fig. 10. indicates the production method of  $RP$  signal or zero crossing detector of current. To compensate the time delay of the circuit elements such as Op Amps, Drivers, Switches, etc., the current compare by 2 positive and negative constant levels. Fig. 11. shows the practical result of the zero crossing circuit.

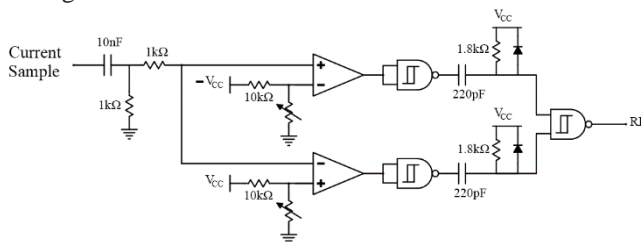


Fig.10. Zero crossing detector circuit

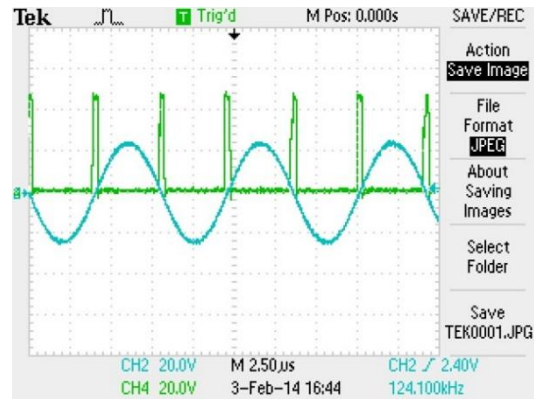


Fig.11. Zero crossing signal

Fig.12. presents the sawtooth waveform generator circuit with constant amplitude. In this figure,  $RP$  is the current zero crossing signal. Fig.13. shows the sawtooth waveform with constant amplitude at frequencies 100 kHz and 180 kHz.

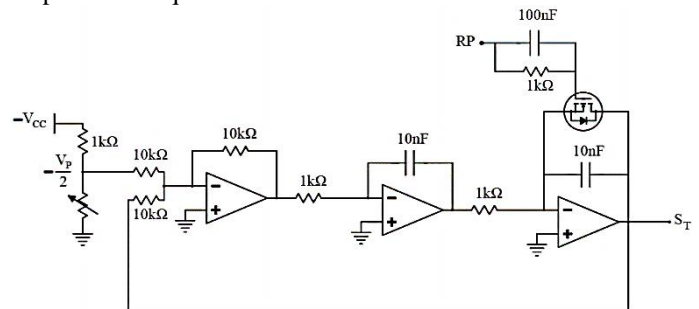


Fig.12.Sawtooth waveform generator circuit

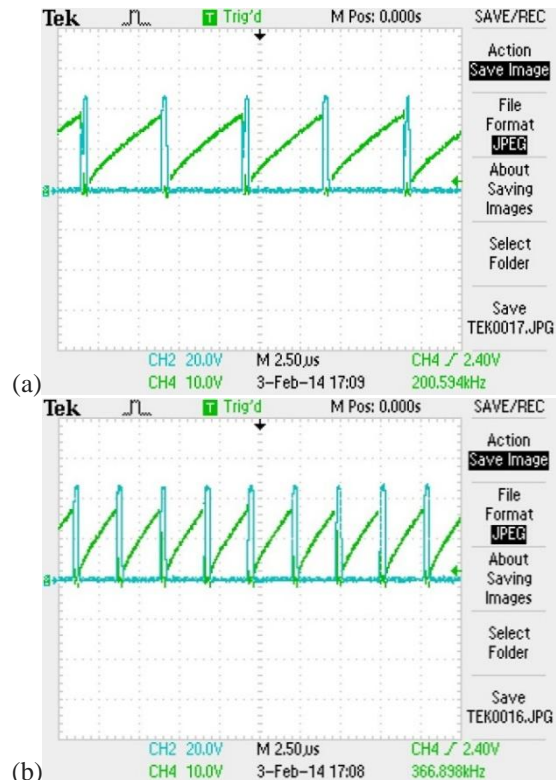


Fig.13.Sawtooth waveform : (a) 100 kHz, (b) 180 kHz

<sup>1</sup> Reset Pulse



### B Control circuit

Fig.14.presents the generationcircuit of gatesignals forthe powerswitches. The“PP” isthe PWM signalof switcheswhich determine duty cycle of theinverter. In this circuit, the current compare by 2 voltage levels. Thus a “JK flip-flop” employed. Gatesignals  $S_1$ - $S_3$ presented in Fig.15.(a) andgatesignals $S_2$ and $S_4$ presented in Fig.15. (b).

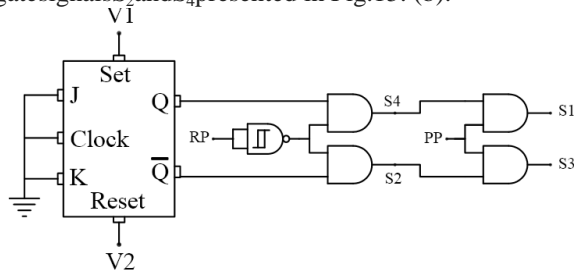


Fig.14. Generation of Gate signals

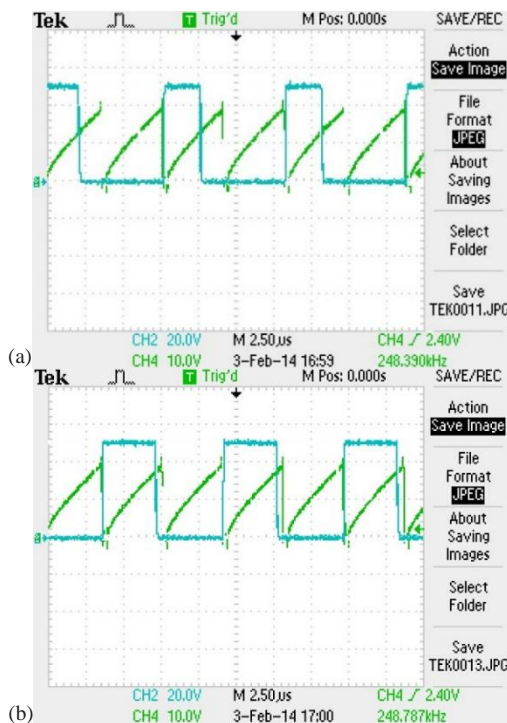


Fig.15. Gate signals: (a)  $S_1$ - $S_3$ , (b)  $S_2$  -  $S_4$

The control board is shown in Fig.16. It contains two main parts: sawtooth generation waveform and power switches gate signals.

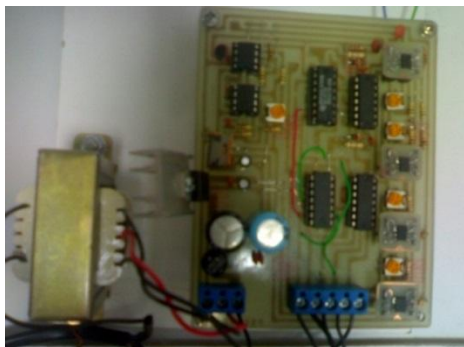


Fig.16. Control board

### C Drivers

One of themain parts ofthe power circuitis the trigger circuit of switches. Topreventthe short circuits in inverter legs,the gate commands have to beisolated. Fig.17 shows the driver circuit. Anopto-coupler is used for isolation of firing signals and IC driver for switching of MOSFETs, theoutput ofthetransformeranddriverhavebeendisplyed in the image below.

### D Power circuit

The implemented circuit contains (Fig.18.): Gate drive circuit with opto-couplers and IC drivers, Inverter with its power switches, resonance circuit, output transformer, rectifier and output capacitors with many capacitor and diodes in series to support high voltage.

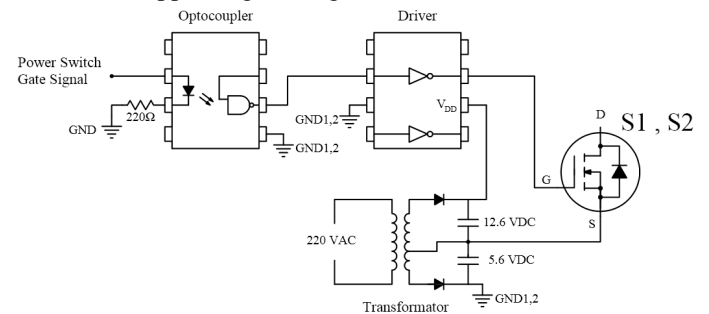


Fig.17. Driver circuit

### E Experimental results

According the laboratory limits and security problems, the system is tested with a 10 V DC power supply. The load resistance is 6200  $\Omega$ .

Fig.19. (a) shows inverter output voltage and current waveforms. In this figure, the square waveform is inverter output voltage and sinusoidal waveform is its current. The peak value of voltage is about 10V and peak current is about 0.7A. Fig.19. (b) shows the output voltage of series-parallel resonant converter which divided by 2. So the real output voltage is 350V. It means that the convert rate of this resonant converter is  $350/10=35$ . If it connects to a power supply with  $220\sqrt{2}$  V, the output voltage will be more than 10 kV.

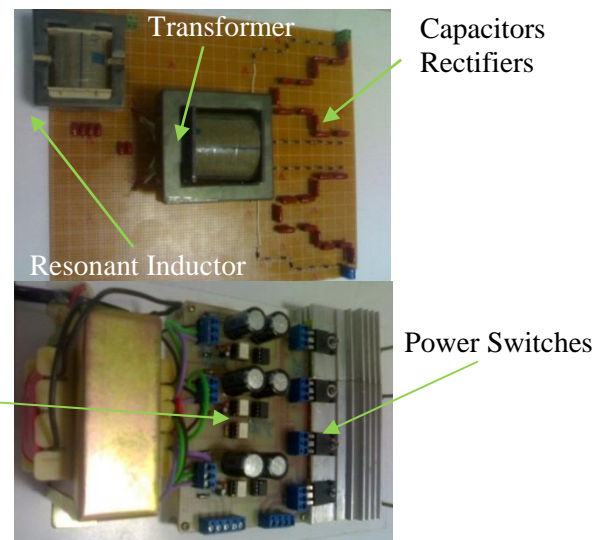


Fig.18. Drivers, inverter switches, resonant elements and transformer

## VII. CONCLUSION

Performance of DC-DC converters with high output voltage is significantly affected by the non-ideal transformer with a high conversion rate and the high number of turns of the secondary. Resonant converters often used in high-voltage DC-DC converters because they can use the leakage inductance and capacitance of coils as resonance circuit elements. In addition, using soft switching techniques in these converters provide the possibility of increasing the efficiency and switching frequency. By increasing the operating frequency, it significantly reduces size and weight of system. In this paper, theoretical analysis on series-parallel resonant converter was performed and the results confirmed by simulation and experimental tests.

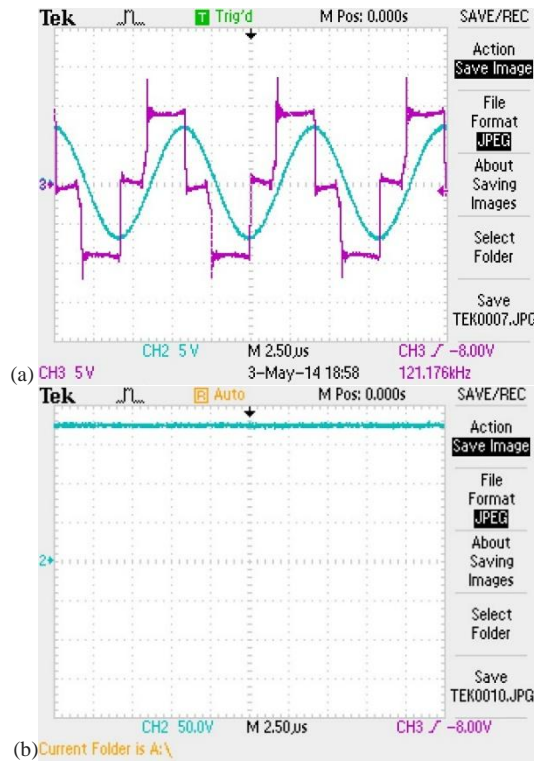


Fig.19. Experimental results: (a) Output voltage (5V/div) and current (0.5A/div) of inverter, (b) Output voltage (divided by 2)

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